



(19)

(11) Publication number: **08086190 A**

Generated Document.

PATENT ABSTRACTS OF JAPAN

(21) Application number: **06219296**

(51) Intl. Cl.: **E21D 9/06 G05B 13/02**

(22) Application date: **13.09.94**

<p>(30) Priority:</p> <p>(43) Date of application publication: 02.04.96</p> <p>(84) Designated contracting states:</p>	<p>(71) Applicant: NIPPON TELEGR & TELEPH CORP <NTT></p> <p>(72) Inventor: KOTANI TADASHI YOSHIDA KOICHI TSUJIMURA TAKESHI YABUTA TETSUO</p> <p>(74) Representative:</p>
---	--

(54) DIRECTION AND POSITION CONTROL METHOD AND DEVICE FOR TUNNEL ROBOT

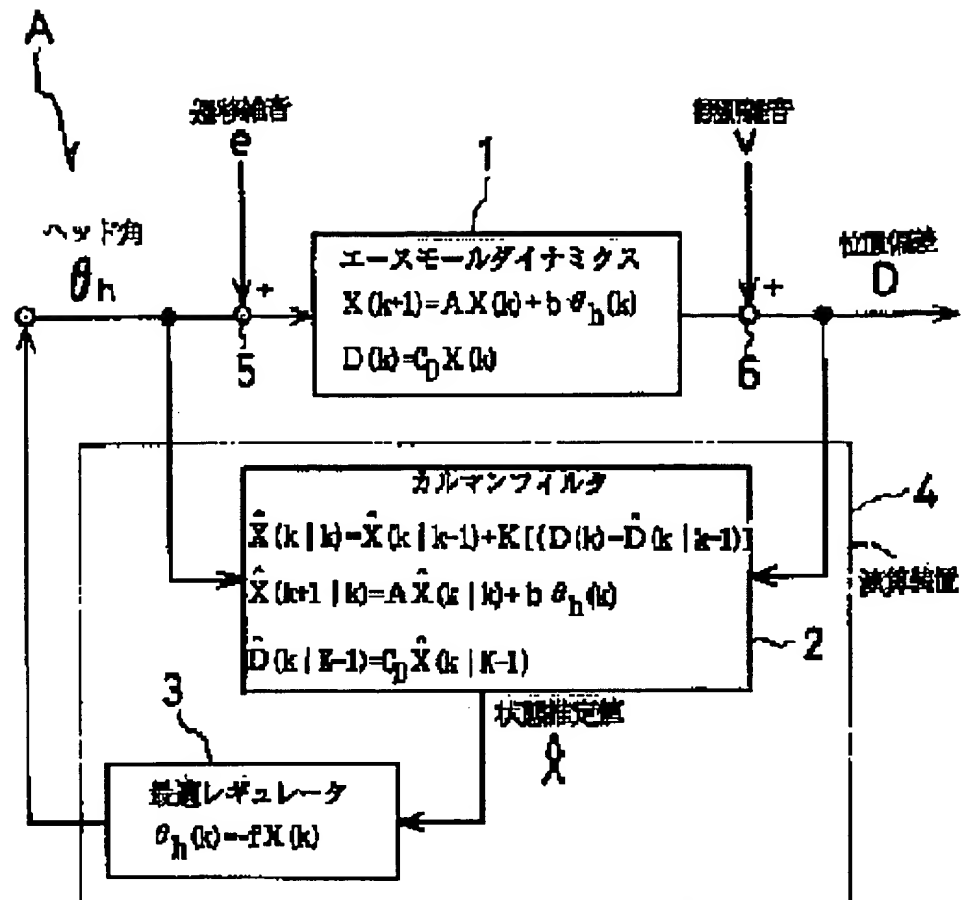
(57) Abstract:

PURPOSE: To correct a route by measuring a position deviation of an underground propulsion robot to be input to a direction and position control device, and feedbacking a head angle computed according to a designated calculation expression by adding a disturbance factor and a measured noise thereto.

CONSTITUTION: At the time of controlling the direction and position of a small bore robot propelled under the ground to construct a non-removed earth pipe line, a position deviation from a planned advancing line is measured from a pressure difference between a pressure sensor in the robot and a pressure sensor on the ground. The measured value is inputted to an acemole dynamics 1 of a control device A to compute a head angle θ_h according to a designated calculation expression. A transition noise produced by soil property change and the like is added to an

adder 5 of the input end of the acemole dynamics 1, and an observation noise at the time of measurement is added to an adder 6 of the output end. The current head angle θ_h and a position deviation D from a planned advacing line estimated at the preceding time are taken in an arithmetic device 4 just before the adder 5 and just after the adder 6 to compute a new head angle θ_h according to a designated calculation expression to feedback the head angle to the robot main body, thereby changing the route.

COPYRIGHT: (C)1996,JPO



BEST AVAILABLE COPY